Multiple solutions of Dirichlet boundary value problems in billiard spaces

> Jan Tomeček Faculty of Science Palacký University Olomouc

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Billiards

Problem formulation and main results

Proofs

• billiard = subset of \mathbb{R}^2 (rectangle, circle, ...),

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- authors investigate the paths of solutions, periodic paths, structure, presence of chaos, ...
- billiards with uneven surface: questions of existence and multiplicity of paths

billiards with uneven surface

[Gabor2016]

Gabor, G.: On the Dirichlet problem in billiard spaces, J. Math. Anal. Appl. 440 (2016) 677–691.

Dirichlet problem in multidimensional case

$$\begin{aligned} x''(t) &= f(t, x(t)), & \text{for a.e.} t \in [0, T], \ x(t) \in \text{int } K, \\ \triangle x'(s) &= I(x(s), x'(s)), & \text{if } x(s) \in \partial K, \\ x(0) &= x(T) = 0. \end{aligned}$$

billiards with uneven surface

[Gabor2016]

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impact law for absolutely elastic impacts (equal angles before and after a collision), i.e. in 1-dim. case:

$$x'(s+) = -x'(s-), \text{ if } |x(s)| = r,$$

- one dimensional case: $K = [-r, r] \subset \mathbb{R}$,
- multidimensional case: K ⊂ ℝ^{2k} has "smooth" boundary, 0 ∈ int K, K is strongly star-shaped,
- there exist infinitely many solutions.
- Proofs: based on shooting method and continuous dependence on initial conditions x(0) = 0, x(0) = d.

billiards with uneven surface

- ▶ in 1D, there is no need of Lipschitz continuity
- there could be said more precise information about the infinite sequence of solutions
- using Schauder Fixed Point Theorem we are able to prove the existence of solutions with prescribed number of impacts
- I have used the transform into nonimpulsive (but singular) problem
- the idea is very simple and well known:



uniform linear motion inside of the segment:

$$x''(t) = 0$$
 if $x(t) \in (0, R)$

absolutely elastic bounce at the boundary:

$$x'(t+) = -x'(t-)$$
 if $x(t) \in \{0, R\}$.

Dirichlet problem:

- ▶ positions $A, B \in (0, R)$ and time instant T > 0 are given
- we seek for solutions in 1D-billiard satisfying

$$x(0) = A, \quad x(T) = B.$$

x	x''=0				
3 <i>R</i>					
2 <i>R</i>					
R				t	
0		Т	7		
-R					

























Therefore the problem

(classicalBIL)

$$egin{aligned} & x''(t) = 0 & ext{if } x(t) \in (0,R), \ & x'(t+) = -x'(t-) & ext{if } x(t) \in \{0,R\}, \ & x(0) = A, \; x(T) = B & (A,B \in (0,R)) \end{aligned}$$



In particular: for each p ∈ N there exist exactly two solutions having exactly p impacts with the boundary.

Therefore the problem

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- In particular: for each p ∈ N there exist exactly two solutions having exactly p impacts with the boundary.
- can we generalize this idea for billiard with uneven billiard or subjected to external forces?

Dirichlet problem in billiard spaces

[Tomecek2019]

J.T.: Multiple solutions of a Dirichlet problem in one-dimensional billiard space, *Math. Notes (Miskolc)*, **20**(2):1261–1272, 2019.

[GaborTomecek2023]

Grzegorz Gabor and J.T.: Multiple solutions of the Dirichlet problem in multidimensional billiard spaces, J Fix Point Theory A **25**, 2023, Article No 7.

[RodriguezLopezTomecek2024]

Jorge Rodríguez-López and J. T.: Second-order discontinuous ODEs and billiard problems. J. Math. Anal. Appl., 536(1):128237, 2024.

Dirichlet problem in billiard spaces

[Gabor2023]

Gabor, G., Tessellation technique in solving the two-point boundary value problem in multidimensional billiard spaces, J. Math. Anal. Appl. **526**:127208,2023

1D billiard problem with velocity dependent RHS

we investigate Dirichlet problem

BIL)

$$\begin{aligned} x'' &= f(t, x, x') & \text{if } x(t) \in (0, R), \\ x'(t+) &= -x'(t-) & \text{if } x(t) \in \{0, R\}, \\ x(0) &= A, \ x(T) = B, \quad (A, B \in (0, R)) \end{aligned}$$

with $f \in Car([0, T] \times [0, R] \times \mathbb{R})$.

[Krajščáková–Tomeček,202?]

Věra Krajščáková, J.T.: Dirichlet problem in one-dimensinal billiard space with velocity dependent right-hand side, submitted.

1D billiard problem with velocity dependent RHS

Theorem

Let $A, B \in (0, R)$, $f \in Car([0, T] \times [0, R] \times \mathbb{R})$ and there exist $m \in L^1([0, T])$ and nonnegative, increasing $\varphi \in \mathbb{C}([0, \infty))$ such that

$$|f(t,x,y)| \le m(t) + \varphi(|y|) \tag{(*)}$$

for a.e. $t \in [0, T]$, all $x \in [0, R]$, $y \in \mathbb{R}$. If there exist $p \in \mathbb{N}$ and L > 0 such that

$$\Psi_1(L) = \frac{T}{R}(\overline{m} + T\varphi(L)) + 1 \le \frac{p}{R} \le \frac{T}{R}(L - \overline{m} - T\varphi(L)) - 1 = \Psi_2(L),$$

where $\overline{m} = \int_0^T m(t) dt$, then there exist at least two solutions of (BIL) having exactly p impacts with the boundary.

Example

$$\begin{aligned} x'' &= t^\alpha + \lambda |x|^\beta \operatorname{sgn} x + \omega |x'|^\gamma \operatorname{sgn} x', \end{aligned}$$
 for
$$T = 1, \ R = 1, \ \alpha = 1, \ \beta = 0.5, \ \gamma = 0.5, \ \omega = 0.5 \text{ and } \lambda = 0.1 \end{aligned}$$



1D billiard problem with velocity dependent RHS

Corollary

Let $A, B \in (0, R)$, $f \in Car([0, T] \times [0, R] \times \mathbb{R})$. Let $m \in L^1([0, T])$ be such that

 $|f(t,x,y)| \leq m(t)$

for a.e. $t \in [0, T]$, all $x \in [0, R]$, $y \in \mathbb{R}$, then for each $p \in \mathbb{N}$ satisfying

$$p \geq \frac{I}{R}\overline{m} + 1,$$

where $\overline{m} = \int_0^T m(t) dt$, there exist at least two solutions of (BIL) having exactly p impacts with the boundary.

... for $\varphi \equiv 0$; *L* can be arbitrarily large ...

1D billiard problem with velocity dependent RHS

Theorem

Let $A, B \in (0, R)$, $f \in \operatorname{Car}([0, T] \times [0, R] \times \mathbb{R})$ satisfy (*) and

$$\limsup_{y\to\infty}\frac{\varphi(y)}{y}<\frac{1}{2T}.$$

Then (BIL) has infinitely many solutions. In particular, there exists an increasing sequence of positive integers $\{p_n\}$ such that for each $n \in \mathbb{N}$ there exists at least two solutions of (BIL) with exactly p_n impacts with the boundary.

... satisfied for sublinear φ ; or linear with small linear coefficient

The proofs

Original problem (BIL):

- ▶ problem on $[0, T] \times [0, R] \times \mathbb{R}$,
- regular RHS,
- problem with (state-dependent) impulses.

Original problem (BIL)

(BIL)

$$\begin{aligned} x'' &= f(t, x, x') & \text{if } x(t) \in (0, R), \\ x'(t+) &= -x'(t-) & \text{if } x(t) \in \{0, R\}, \\ x(0) &= A, \ x(T) = B, \quad (A, B \in (0, R)) \end{aligned}$$

where $f \in Car([0, T] \times [0, R] \times \mathbb{R})$.

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- ▶ problem on $[0, T] \times [0, R] \times \mathbb{R}$,
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- Extended problems (EXT):
 - problem on $[0, T] \times \mathbb{R} \times \mathbb{R}$,
 - non-impulsive problem,
 - singular RHS; possibly unbounded in the last variable.

Construction of (EXT)

New right-hand side of ODE,

the extension of f:

$$f^{*}(t, x, y) = \begin{cases} f(t, x - 2kR, y) \\ \text{if } x \in (2kR, (2k+1)R), \\ -f(t, 2(k+1)R - x, -y) \\ \text{if } x \in ((2k+1)R, 2(k+1)R) \\ 0, \quad \text{if } x = kR, \ k \in \mathbb{Z} \end{cases}$$

odd, 2R-periodic in the second variable

Construction of (EXT)

• We define a folding function Δ :

$$\Delta(s) = egin{cases} s - 2kR & ext{if } s \in [2kR, (2k+1)R), \ 2(k+1)R - s & ext{if } s \in [(2k+1)R, 2(k+1)R). \end{cases}$$



• $\Delta : \mathbb{R} \to [0, R]$, idempotent, 2*R*-periodic, continuous.

We consider these extended problems

(EXT)

$$y'' = f^*(t, y, y')$$

 $y(0) = A, \quad y(T) = \tilde{B}$

where

$$\Delta(\tilde{B})=B,$$

i.e.

$$ilde{B} = B, \ 2R - B, \ 2R + B, \ \ldots, \ -B, \ -2R + B, \ \ldots$$

Lemma: (EXT) \rightarrow (BIL)

If $y \in (EXT)$ is strictly monotone, then

 $\Delta \circ y$

solves (BIL) having exactly

$$\left\lfloor \frac{A}{R} \right\rfloor - \left\lfloor \frac{\tilde{B}}{R} \right\rfloor$$

impacts with the boundary.

Lemma: $(EXT) \rightarrow (BIL)$

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Spoiler: Yes, if \tilde{B} is in an appropriate distance from A.

But, first we define two more auxiliary problems.

The proofs

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- ▶ problem on $[0, T] \times [0, R] \times \mathbb{R}$,
- regular RHS,
- problem with (state-dependent) impulses.
- Extended problems (EXT):
 - problem on $[0, T] \times \mathbb{R} \times \mathbb{R}$,
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 - problem on $[0, T] \times \mathbb{R} \times \mathbb{R}$,
 - non-impulsive problem,
 - singular RHS; possibly unbounded in the last variable.
- Truncated problems in the last variable (TRUNC):
 - class of problems on $[0, T] \times \mathbb{R} \times \mathbb{R}$
 - bounded in the last variable,
 - depending on a real parameter L
 - but still singular RHS.

Construction of (TRUNC)

Truncation of f^* in the last variable: for each L > 0 we define

$$f_{L}^{*}(t, x, y) = f^{*}(t, x, \max\{-L, \min\{y, L\}\})$$

f_L^{*} is bounded by a Lebesgue integrable function over [0, T]
 it is still singular in x

(TRUNC)

$$y'' = f_L^*(t, y, y').$$

$$y(0) = A, \quad y(T) = \tilde{B}$$

 $\begin{array}{ll} y \in (\mathsf{TRUNC}) \ \land \ |y'| \leq L \implies & y \in (\mathsf{EXT}) \\ y \in (\mathsf{TRUNC}) \ \land \ |y'| \leq L \ \land \ y' \neq 0 \implies & \Delta \circ y \in (\mathsf{BIL}) \end{array}$

The proofs

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- Regularized problems (REG(n)):
 - sequence of regular problems on $[0, T] \times \mathbb{R} \times \mathbb{R}$,
 - non-impulsive problem,
 - regular RHS.

Construction of (REG(n))

▶ $f_L^*(t, x, y)$ has possible discontinuity at x = kR (each $k \in \mathbb{Z}$)

Construction of (REG(n))

f^{*}_L(*t*, *x*, *y*) has possible discontinuity at *x* = *kR* (each *k* ∈ ℤ)
 we define regularizing functions η_n : ℝ → ℝ



Construction of (REG(n))

f^{*}_L(t, x, y) has possible discontinuity at x = kR (each k ∈ ℤ)
 we define regularizing functions η_n : ℝ → ℝ



▶ *R*-periodic; continuous; zero at *kR*, $k \in \mathbb{Z}$; $\eta_n \rightarrow 1$ on (0, R).

For $n \in \mathbb{N}$ we consider

 $(\mathsf{REG}(n))$

$$z'' = \eta_n(z) f_L^*(t, z, z'),$$

$$z(0) = A, \quad z(T) = \frac{\tilde{B}}{B}.$$



For $n \in \mathbb{N}$ we consider

 $(\mathsf{REG}(n))$

$$z'' = \eta_n(z) f_L^*(t, z, z'),$$

$$z(0) = A, \quad z(T) = \tilde{B}.$$

regular RHS

for each A, B̃ ∈ ℝ and n ∈ ℕ there exists at least one solution of (REG(n)), z_n (⇐ Schauder FPT).

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 $(\mathsf{REG}(n))$

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$$z(0) = A, \quad z(T) = \tilde{B}.$$

regular RHS

for each A, B̃ ∈ ℝ and n ∈ ℕ there exists at least one solution of (REG(n)), z_n (⇐ Schauder FPT).

$$\frac{\tilde{B}-A}{T}-\overline{m}-T\varphi(L)\leq z_n'(t)\leq \frac{\tilde{B}-A}{T}+\overline{m}+T\varphi(L),$$

 $t\in [0, T], n\in \mathbb{N}.$

•
$$z_{k_n} \rightarrow z$$
 in C^1 , $z_{k_n} \in (REG(k_n))$ (\leftarrow Arzelà-Ascoli)

►
$$z_{k_n} \rightarrow z$$
 in C^1 , $z_{k_n} \in (REG(k_n))$ (\Leftarrow Arzelà-Ascoli)
► $\frac{\tilde{B} - A}{T} - \overline{m} - T\varphi(L) \le z'(t) \le \frac{\tilde{B} - A}{T} + \overline{m} + T\varphi(L)$,
 $t \in [0, T]$,
► if $0 < \frac{\tilde{B} - A}{T} - \overline{m} - T\varphi(L) \& \frac{\tilde{B} - A}{T} + \overline{m} + T\varphi(L) \le L$,
then $z \in (\text{TRUNC}) \& 0 < z' \le L \Rightarrow \Delta \circ z \in (\text{BIL})$ (!!!)

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