

## On Bounded Monotone Solutions to Singular in the Time Variable Two-Dimensional Differential Systems

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In the present report, for singular in the time variable differential systems

$$u'_i = f_i(t, u_1, u_2) \quad (i = 1, 2), \quad (1)$$

$$u'_i = g_i(t, u_{3-i}) \quad (i = 1, 2), \quad (1')$$

we consider the problem on the existence of so-called Kneser solution, defined on the positive half-axis, and satisfying the initial condition

$$\lim_{t \rightarrow 0} u_1(t) = c.$$

Conditions that are unimprovable in a certain sense are given, guaranteeing, respectively, the existence, uniqueness, monotonicity, boundedness, and vanishment at infinity of a solution to this problem.

We use the following notation:  $\mathbb{R} = \{-\infty, +\infty\}$ ,  $\mathbb{R}_+ = [0, +\infty[$ ,  $\mathbb{R}_- = ]-\infty, 0]$ .

$L_{loc}(I)$ , where  $I$  is either open or semi-open interval, is the space of defined in  $I$  real functions whose restrictions to any closed bounded interval contained in  $I$  are Lebesgue integrable.

We say that the function  $f : I \times \mathbb{R}^m \rightarrow \mathbb{R}$  belongs to the Carathéodory space  $K_{loc}(I \times \mathbb{R}^m)$  if the function  $f(\cdot, x_1, \dots, x_m) : I \rightarrow \mathbb{R}$  is measurable for any arbitrarily fixed  $(x_1, \dots, x_m) \in \mathbb{R}^m$ , the function  $f(t, \cdot, \dots, \cdot) : \mathbb{R}^m \rightarrow \mathbb{R}$  is continuous for almost all arbitrarily fixed  $t \in I$ , and

$$\max \left\{ |f(\cdot, x_1, \dots, x_m)| : \sum_{i=1}^m |x_i| \leq x \right\} \in L_{loc}(I)$$

for every positive constant  $x$ .

We investigate systems (1) and (1') in the case, where  $f_1 \in K_{loc}(\mathbb{R}_+ \times \mathbb{R}^2)$ ,  $f_2 \in K_{loc}(]0, +\infty[ \times \mathbb{R}^2)$ , and the conditions

$$f_i(t, 0, 0) = 0, \quad (-1)^i f_i(t, x_1, x_2) \geq 0 \quad \text{for } t > 0, \quad x_1 \in \mathbb{R}_+, \quad x_2 \in \mathbb{R}_- \quad (i = 1, 2),$$

$$g_1 \in K_{loc}(\mathbb{R}_+ \times \mathbb{R}), \quad g_2 \in K_{loc}(]0, +\infty[ \times \mathbb{R}),$$

$$g_i(t, y) \geq g_i(t, x), \quad g_i(t, -x) = -g_i(t, x) \quad \text{for } t > 0, \quad y \geq x \quad (i = 1, 2)$$

are satisfied. At the same time, we do not exclude cases where the differential systems under consideration have non-integrable singularities in the time variable at the point  $t = 0$ , namely, the cases, where

$$\int_0^1 f_2(t, x_1, x_2) dt = +\infty, \quad \int_0^1 g_2(t, x_1) dt = +\infty \quad \text{for } x_1 > 0, \quad x_2 < 0.$$