

# On the Cauchy–Nicoletti Weighted Problem for Nonlinear Singular Functional Differential Systems

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Let  $-\infty < a < b < +\infty$ ,  $t_i \in [a, b]$  ( $i = 1, \dots, n$ ),  $\varphi = (\varphi_i)_{i=1}^n : [a, b] \rightarrow \mathbb{R}^n$  be a continuous vector function such that

$$\varphi_i(t_i) = 0, \quad \varphi_i(t) > 0 \text{ for } t \neq t_i \quad (i = 1, \dots, n),$$

and let  $C_\varphi([a, b]; \mathbb{R}^n)$  be the space of continuous vector functions  $x = (x_i)_{i=1}^n : [a, b] \rightarrow \mathbb{R}^n$ , satisfying the condition

$$\|x\|_{C_\varphi} = \sum_{i=1}^n \|x_i\|_{C_{\varphi_i}} < +\infty,$$

where

$$\|x_i\|_{C_{\varphi_i}} = \sup \left\{ \frac{|x_i(t)|}{\varphi_i(t)} : a \leq t \leq b, t \neq t_i \right\} \quad (i = 1, \dots, n).$$

Let, moreover,  $I_k = [a, b] \setminus \{t_k\}$  ( $k = 1, \dots, n$ ), and  $L_{loc}(I_k; \mathbb{R})$  be the space of functions  $u : I_k \rightarrow \mathbb{R}$ , Lebesgue integrable on every closed interval, contained in  $I_k$ .

We consider the nonlinear functional differential system

$$\frac{dx_i(t)}{dt} = f_i(x_1, \dots, x_n)(t) \quad (i = 1, \dots, n) \quad (1)$$

with the weighted boundary conditions

$$\limsup_{t \rightarrow t_i} \frac{|x_i(t)|}{\varphi_i(t)} < +\infty \quad (i = 1, \dots, n). \quad (2)$$

Here the operators  $f_k : C_\varphi([a, b]; \mathbb{R}^n) \rightarrow L_{loc}(I_k; \mathbb{R})$  ( $k = 1, \dots, n$ ) are such that:

(i) for any  $\rho > 0$ , the condition

$$f_k^*(\varphi, \rho) \in L_{loc}(I_k; \mathbb{R}) \quad (k = 1, \dots, n)$$

is satisfied, where

$$f_k^*(\varphi, \rho)(t) = \sup \left\{ |f_k(x_1, \dots, x_n)(t)| : \|(x_i)_{i=1}^n\|_{C_\varphi} \leq \rho \right\};$$

(ii) for any  $\rho > 0$ ,  $k \in \{1, \dots, n\}$ ,  $[a_0, b_0] \subset I_k$ , and uniformly converging sequence of continuous vector functions  $(x_{im})_{i=1}^n : [a, b] \rightarrow \mathbb{R}^n$  ( $m = 1, 2, \dots$ ), satisfying the conditions

$$\begin{aligned} \|(x_{im})_{i=1}^n\|_{C_\varphi} &\leq \rho \quad (m = 1, 2, \dots), \\ \lim_{m \rightarrow \infty} (x_{im}(t))_{i=1}^n &= (x_i(t))_{i=1}^n \quad \text{for } t \in [a, b], \end{aligned} \quad (3)$$

we have

$$\begin{aligned} &\lim_{m \rightarrow \infty} \int_{a_0}^t f_k(x_{1m}, \dots, x_{nm})(s) ds \\ &= \int_{a_0}^t f_k(x_1, \dots, x_n)(s) ds \quad \text{uniformly on } [a_0, b_0]. \end{aligned}$$

We are interested in the case where system (1) is singular, i.e. the case where

$$\int_a^b \left( \sum_{k=1}^n f_k^*(\varphi, \rho)(t) \right) dt = +\infty \quad \text{for any } \rho > 0.$$

From (2) we have the conditions

$$x_i(t_i) = 0 \quad (i = 1, \dots, n). \quad (4)$$

Problem (1), (2) we call the Cauchy–Nicoletti weighted problem since problem (1), (4) is known as the Cauchy–Nicoletti problem (see, [1, 2, 4, 6, 7]).

By I. Kiguradze [2, 3], the optimal sufficient conditions are obtained for the solvability and unique solvability of the Cauchy–Nicoletti weighted problem for systems of ordinary differential equations with singularities with respect to a time variable at the points bearing the boundary data. In the present work, these results are generalized for functional differential systems. Precisely, unimprovable in a certain sense conditions are established guaranteeing, respectively, the solvability and unsolvability of problem (1), (2) and the stability of its solution with respect to small perturbations of the right-hand sides of system (1).

Everywhere below, in addition to the above-introduced notation, we will also use the following notation.

$X = (x_{ik})_{i,k=1}^n$  is the  $n \times n$  matrix with components  $x_{ik}$  ( $i, k = 1, \dots, n$ ).

$r(X)$  is the spectral radius of an  $n \times n$  matrix  $X$ .

$[x]_+$  is the positive part of a real number  $x$ , i.e.,  $[x]_+ = (x + |x|)/2$ .

For any  $i \in \{1, \dots, n\}$ ,  $\delta > 0$ , and  $\lambda \in [0, 1]$ , we set

$$\chi_i(t, \delta, \lambda) = \begin{cases} 0 & \text{for } t \in [t_i - \delta, t_i + \delta], \\ \lambda & \text{for } t \notin [t_i - \delta, t_i + \delta], \end{cases}$$

and along with (1) we consider the auxiliary differential system

$$\frac{dx_i(t)}{dt} = \chi_i(t, \delta, \lambda) f_i(x_1, \dots, x_n)(t) \quad (i = 1, \dots, n). \quad (5)$$

On the basis of Corollary 2 from [5], the following theorem can be proved.

**Theorem 1** (The principle of a priori boundedness). *Let there exist a positive number  $\rho$  such that for any  $\lambda \in [0, 1]$  and  $\delta > 0$  every solution of problem (5), (4) admits estimate (3). Then problem (1), (2) has at least one solution.*

This theorem enables us to establish efficient sufficient conditions for the solvability of problem (1), (2).

In particular, the following theorem is valid.

**Theorem 2.** *Let there exist nonnegative numbers  $p_{ik}$  ( $i, k = 1, \dots, n$ ) and a function  $q : [0, +\infty[ \rightarrow [0, +\infty[$  such that*

$$r(P) < 1, \quad \text{where } P = (p_{ik})_{i,k=1}^n, \quad (6)$$

$$\lim_{s \rightarrow +\infty} \frac{q(s)}{s} = 0,$$

and for any  $(x_i)_{i=1}^n \in C_\varphi([a, b]; \mathbb{R}^n)$  the inequalities

$$\left| \int_{t_i}^t [f_i(x_1, \dots, x_n)(s) \operatorname{sgn}((s - t_i)x_i(s))]_+ ds \right|$$

$$\leq \varphi_i(t) \left( \sum_{k=1}^n p_{ik} \|x_k\|_{C_{\varphi_k}} + q \left( \sum_{k=1}^n \|x_k\|_{C_{\varphi_k}} \right) \right) \quad (i = 1, \dots, n)$$

are satisfied in the interval  $[a, b]$ . Then problem (1), (2) has at least one solution.

We consider now the perturbed problem

$$\frac{dy_i(t)}{dt} = f_i(y_1, \dots, y_n)(t) + h_i(t) \quad (i = 1, \dots, n), \quad (7)$$

$$\limsup_{t \rightarrow t_i} \frac{|y_i(t)|}{\varphi_i(t)} < +\infty \quad (i = 1, \dots, n), \quad (8)$$

and we introduce the following

**Definition.** Problem (1), (2) is said to be well-posed if:

- (i) it has a unique solution  $(x_i)_{i=1}^n$ ;
- (ii) there exists a positive constant  $\rho$  such that for any integrable functions  $h_i : ]a, b[ \rightarrow \mathbb{R}$  ( $i = 1, \dots, n$ ), satisfying the conditions

$$v_k(h_k) = \sup \left\{ \frac{1}{\varphi_k(t)} \left| \int_{t_k}^t |h_k(s)| ds \right| : a \leq t \leq b, t \neq t_k \right\} < +\infty \quad (k = 1, \dots, n),$$

problem (7), (8) has at least one solution and every such solution admits the estimate

$$\left\| (y_i - x_i)_{i=1}^n \right\|_{C_\varphi} \leq \rho \sum_{k=1}^n v_k(h_k).$$

**Theorem 3.** Let there exist nonnegative numbers  $p_{ik}$  ( $i, k = 1, \dots, n$ ), satisfying condition (6), such that for any  $(x_i)_{i=1}^n \in C_\varphi([a, b]; \mathbb{R}^n)$ , in the interval  $[a, b]$  the inequalities

$$\left| \int_{t_i}^t [f_i(x_1, \dots, x_n)(s) \operatorname{sgn}((s - t_i)x_i(s))]_{+} ds \right| \leq \varphi_i(t) \sum_{k=1}^n p_{ik} \|x_k\|_{C_{\varphi_k}} \quad (i = 1, \dots, n)$$

are fulfilled. Then problem (1), (2) is well-posed.

## References

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